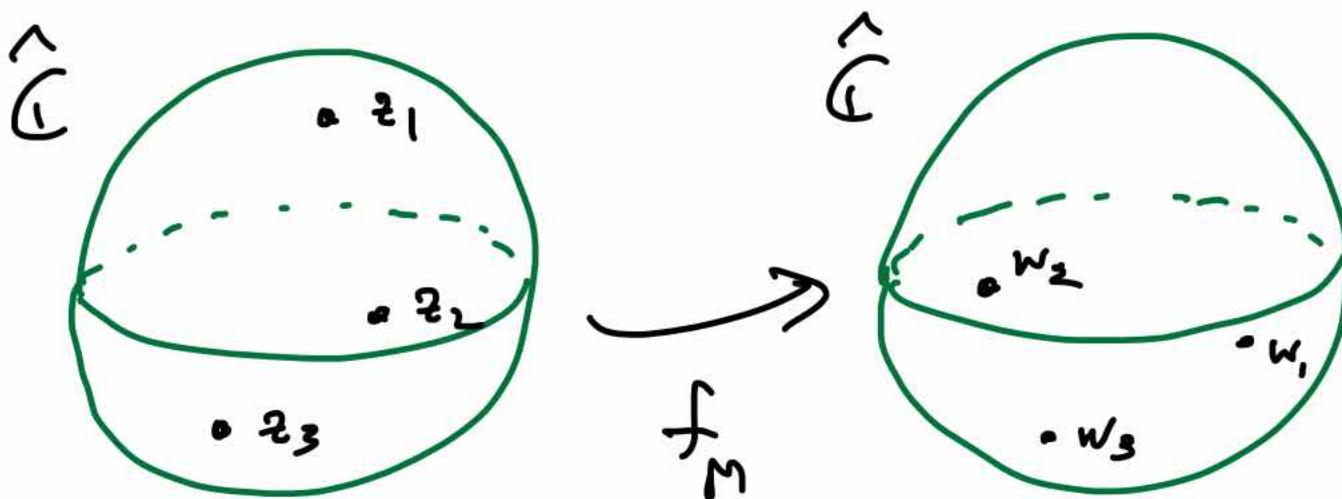


Lecture II : Conformal Mappings

We continue our discussion of FLTs (= fractional linear transformations), then consider a generalization.

I. Cross-ratio



Recall that there exists a unique $f_M \in \underline{\text{FLT}}$ taking $z_i \mapsto w_i$ ($\forall i$). In the special case where $\{w_i\}$ are $1, 0, \infty$, this is

$$f(z) = \frac{z - z_2}{z - z_3} \cdot \frac{z_1 - z_3}{z_1 - z_2} =: \text{CR}(z, z_1, z_2, z_3)$$

which tells us where z is sent by the FLT taking the last 3 entries to $1, 0, \infty$ (in that order).

Theorem

(a) CR is invariant under FLTs :

if $g \in \underline{\text{FLT}}$, then

$$(*) \quad CR(g(z), g(z_1), g(z_2), g(z_3)) = CR(z, z_1, z_2, z_3).$$

(b) z, z_1, z_2, z_3 belong to the same $C \in \mathcal{C}$

$$\iff CR(z, z_1, z_2, z_3) \in R.$$

Proof : (a) fog^{-1} sends $g(z_1), g(z_2), g(z_3) \mapsto 1, 0, \infty$.

$$\text{So } LHS(*) = (fog^{-1})(g(z)) = f(z) = RHS(*) .$$

(b) (\implies): If z lies on $C := C_{(z_1, z_2, z_3)}$,

then (by transitivity of action of $\underline{\text{FLT}}$ on \mathcal{C}) $\exists F \in \underline{\text{FLT}}$

taking C into R . But then

$$CR(z, z_1, z_2, z_3) = CR(F(z), F(z_1), F(z_2), F(z_3)) \in R.$$

(cf. Corollary from Lect. 10)

\Leftarrow : Let $G \in \underline{\text{FLT}}$ send $1, 0, \infty$

to z_1, z_2, z_3 hence $\mathbb{R} \rightarrow G := G_{(z_1, z_2, z_3)}$.

Then $f^{-1}(z) = CR(G^{-1}(z), \underbrace{1, 0, \infty}_{G^{-1}(z_1), G^{-1}(z_2), f^{-1}(z_3)}) \in \mathbb{R}$

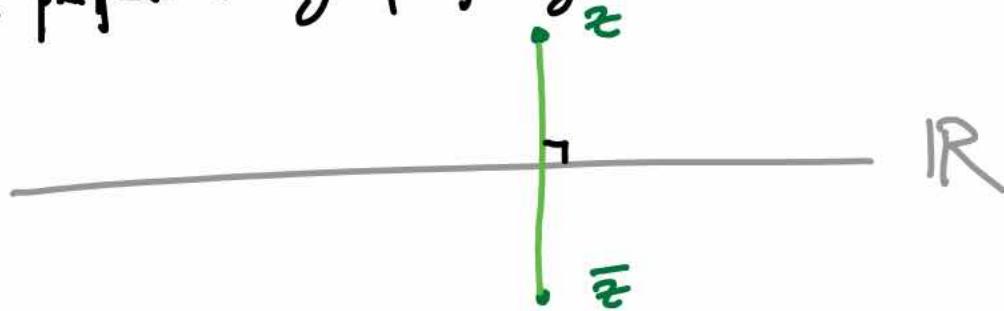
$$G^{-1}(z_1), G^{-1}(z_2), f^{-1}(z_3)$$

$\Rightarrow z = G(f^{-1}(z)) \in G(\mathbb{R}) = G$.

□

II. Symmetry and Orientation

Complex conjugation is a reflection about \mathbb{R} ,
with the "perpendicularity property" shown in the picture:



Are there corresponding reflections about arbitrary $G \in \mathcal{C}$?

Let $F \in \underline{\text{FLT}}$ take $\mathbb{R} \rightarrow G$, & define

$$z_G^* := F(\overline{F^{-1}(z)}) = (F \circ \bar{F}^{-1})(\bar{z}).$$

(Here the bar denotes complex conjugation, and \bar{F} means \tilde{F}_M if $F = F_M$.) Given any other $\tilde{F} \in \underline{\text{FLT}}$

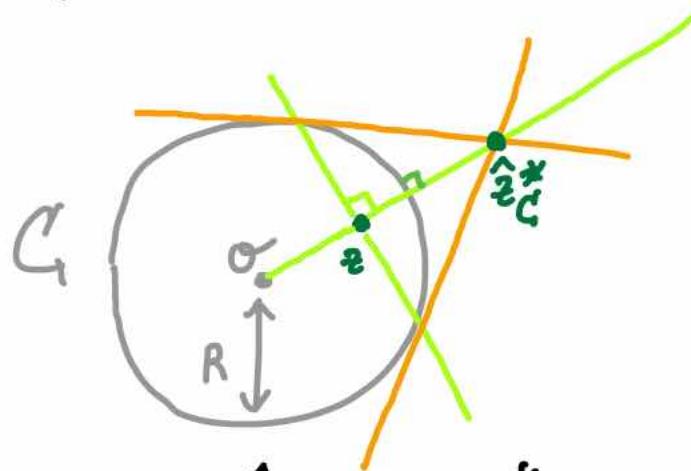
taking $R \rightarrow G$,

$$F^{-1} \circ \tilde{F} = f_M, \quad M \in SL_2(\mathbb{R}).$$

$$\begin{aligned} \text{So } \tilde{F} &= F \circ f_M \Rightarrow \tilde{F}(\tilde{F}^{-1}(\bar{z})) \\ &= F(f_M(\tilde{F}^{-1}(\tilde{F}^{-1}(\bar{z})))) \\ &\stackrel{\text{circle}}{=} F(\tilde{F}^{-1}(\bar{z})) \\ \tilde{f}_M &= f_M \end{aligned}$$

and \hat{z}_G^* is well-defined.

The above picture holds for any line, since we can take F to be a composite of rotation/dilations and translations. For any line or circle, $(\cdot)_G^*$ fixes points on G . Now consider Ahlfors's construction



We will show that $\hat{z}_G^* = z_G^*$. First, we claim that $d(z, o) \cdot d(z_G^*, o) = R$. [It suffices to check everything for $G = \{ |z| = 1 \}$ (since we can translate the center to O and dilate), where

$R=1$. The FLT $z \mapsto \frac{z-i}{z+i} = F(z)$ sends $\mathbb{R} \rightarrow \partial D_1$,

and has $F^{-1}(z) = \frac{i(1+z)}{1-z}$, so

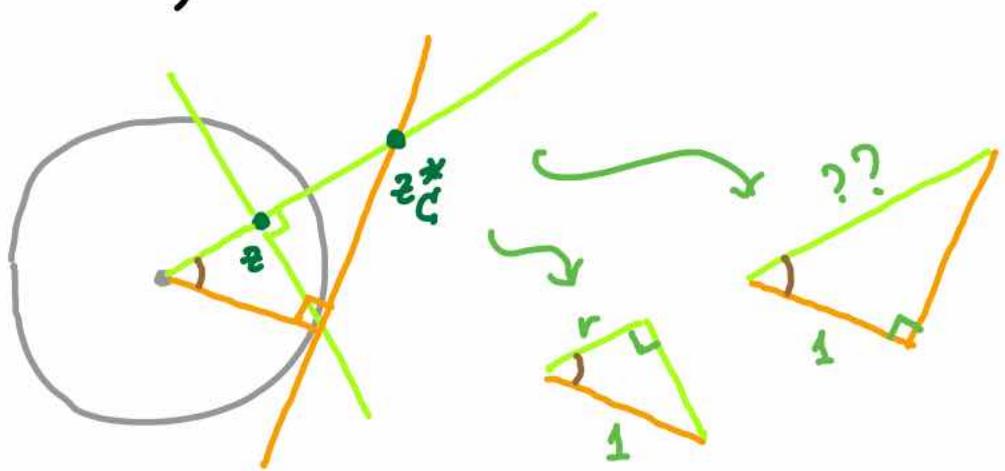
$$F(\overline{F^{-1}(z)}) = \frac{-\frac{i(1+\bar{z})}{1-\bar{z}} - i}{-\frac{i(1+\bar{z})}{1-\bar{z}} + i} = \dots = \frac{1}{z};$$

that is,

$$(re^{i\theta})^*_{\partial D_1} = \frac{1}{re^{-i\theta}} = \frac{1}{r}e^{i\theta},$$

confirming the claim.]

Now taking $z=re^{i\theta}$, consider the similar triangles

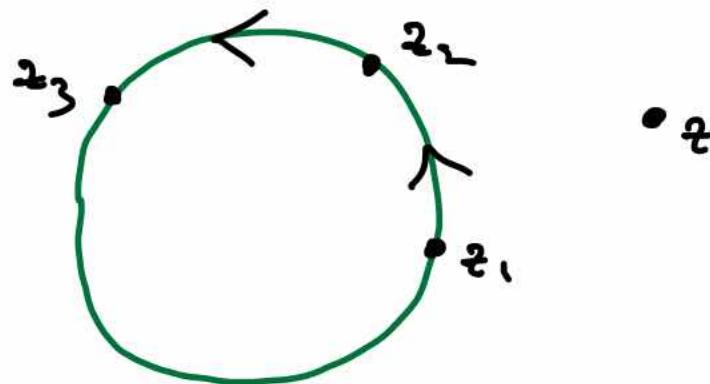


Clearly the "???" edge has length $\frac{1}{r}$, and so

$\hat{z}_C^* = \frac{1}{r} e^{i\theta} \stackrel{\text{as promised.}}{=} z^*_{\partial D_1}$ as promised. The geometric picture now makes it clear that the segment connecting z_C^* and z meets C orthogonally.

Moreover, they lie on different "sides" of C . If we use the

Ordering of z_1, z_2, z_3 on C to give it an orientation



then

- z is to the right of the ^(oriented) circle \Leftrightarrow

$$\operatorname{Im}(CR(z, z_1, z_2, z_3)) > 0$$

- z is to the left of the ^(oriented) circle \Leftrightarrow

$$\operatorname{Im}(CR(z, z_1, z_2, z_3)) < 0.$$

The circle is oriented counterclockwise if ∞ is to the right.

III. Fixed points

Let $f(z) = \frac{\alpha z + \beta}{\gamma z + \delta}$. A fixed point of f is

a solution to the equation

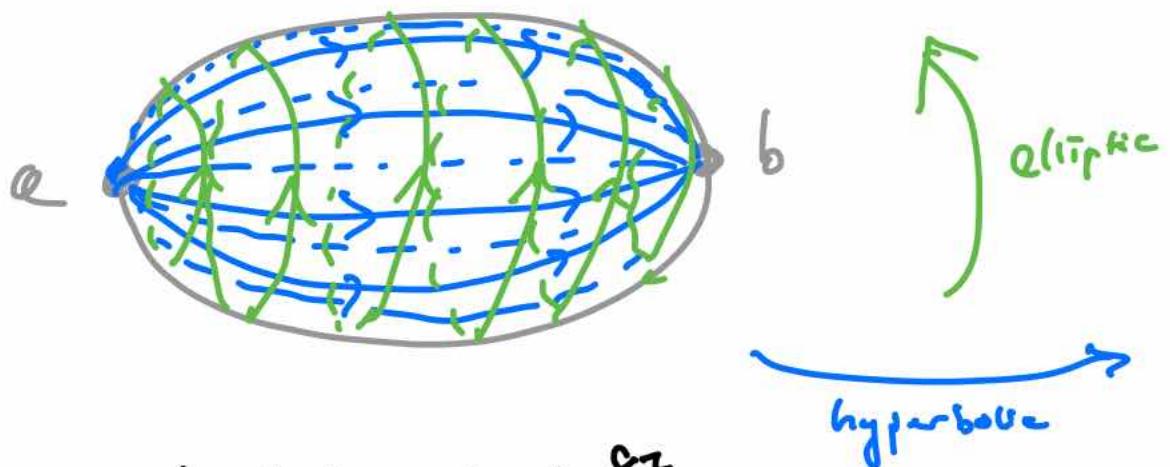
$$z = \frac{\alpha z + \beta}{\gamma z + \delta}$$

$$\text{or (equiv.) } \gamma z^2 + (\delta - \alpha)z - \beta = 0$$

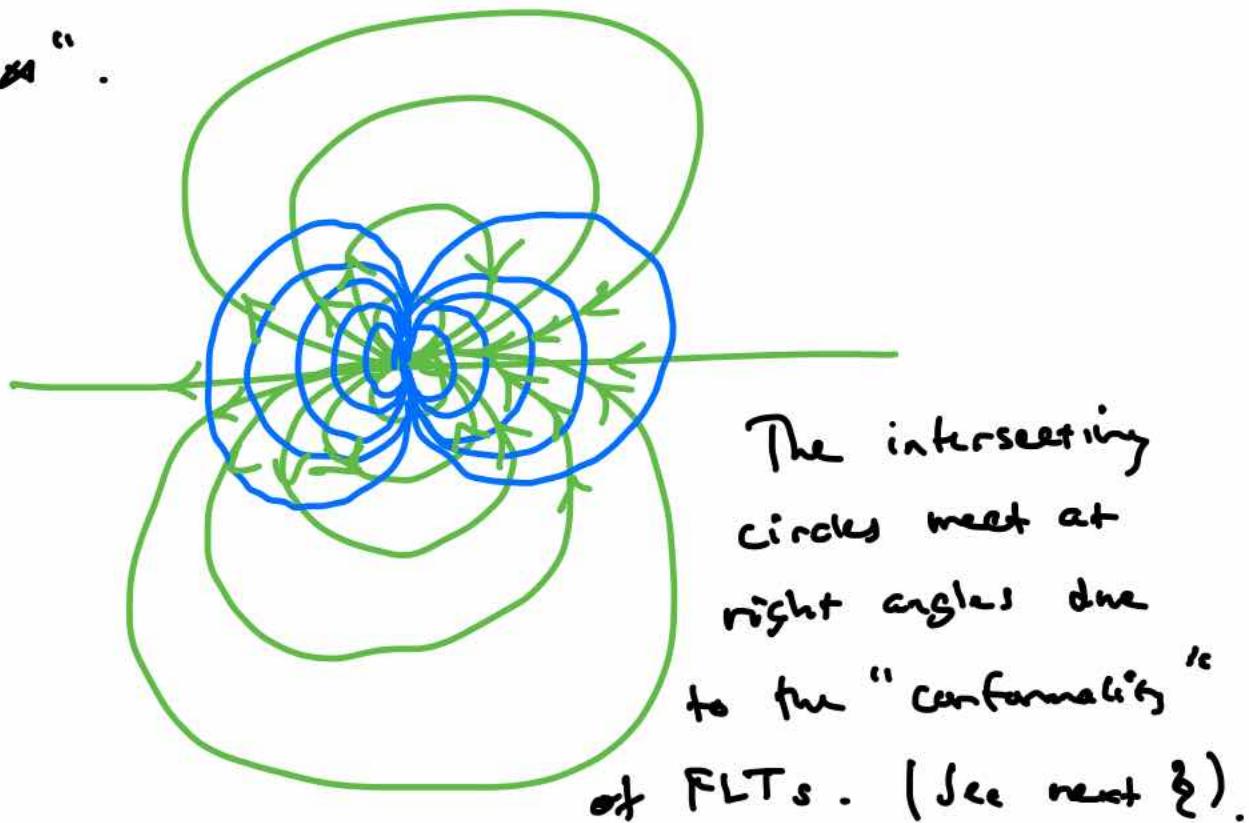
$$z = \frac{\alpha - \delta \pm \sqrt{(\delta - \alpha)^2 + 4\gamma\beta}}{2\gamma}.$$

- If $\gamma = 0$ then one or both FP's (counted w/
multiplicity) are at ∞ . In this case, f is "affine" or
"loxodromic."
- If $\gamma \neq 0$ and $(\delta - \alpha)^2 = -4\gamma\beta$ then there is one
(finite) FP with multiplicity 2, and f is "parabolic."
- If there are 2 distinct finite roots, then call them a & b , and take σ to be an FLT sending $a, b \mapsto 0, \infty$ (e.g. $\sigma(z) = \frac{z-a}{z-b}$). Then $\sigma \circ f \circ \sigma^{-1}$ fixes $0 \& \infty$. (Note that this simply diagonalizes the corresponding matrix.) The FLTs fixing $0 \& \infty$ are just the μ_ξ ($\xi \in \mathbb{C}^\times$): dilation-rotations.
So $\sigma \circ f \circ \sigma^{-1} = \mu_\xi$. If $\xi \in \mathbb{R}^\times$ then f is
"hyperbolic"; if $\xi \in S^1$ "elliptic"; otherwise (again)
"loxodromic".

Remark : (a) The pictures of circles on p. 85 of Ahlfors are just the image under $z \mapsto \frac{z-a}{z-b}$ (sends $0, \infty \mapsto a, b$) of polar coordinate lines. The meaning is clearer on $\hat{\mathbb{C}}$:



(b) The pictures of conics on p. 87 are just "a view of Cartesian coordinates from ∞ ", and the transformations he describes are just "translations seen from ∞ ".



(c) The transformation

$$\begin{array}{c} (\cos \theta) \pm i \sin \theta \\ \hline -(\sin \theta) \pm i \cos \theta \end{array}$$

fixes $i\theta - i$. Diagonalizing the corresponding matrix, or just computing the characteristic polynomial, you find the eigenvalues are $\cos \theta \pm i \sin \theta$, i.e. $|\mathfrak{z}| = 1$ \Rightarrow elliptic. (In general, \mathfrak{z} is just the ratio of the eigenvalues.)

In Iwasawa, $N \leftrightarrow$ affine (or parabolic if you count so as a legitimate FP)
 $A \leftrightarrow$ affine (or hyperbolic if \dots \dots \dots)

$K \leftrightarrow$ elliptic.

(d) In fact, I would propose the following (revised) terminology: working mod $\pm id$, with $M \in SL_2(\mathbb{C})$,

f_M elliptic $\Leftrightarrow M$ conjugate to $\begin{pmatrix} e^{i\theta} & 0 \\ 0 & e^{-i\theta} \end{pmatrix}$ ($\theta \in \mathbb{R}$)

f_M hyperbolic $\Leftrightarrow M$ conjugate to $\begin{pmatrix} r & 0 \\ 0 & r^{-1} \end{pmatrix}$ ($r \in \mathbb{R}_{>0}$)

f_M parabolic $\Leftrightarrow M$ conjugate to $\begin{pmatrix} 1 & \alpha \\ 0 & 1 \end{pmatrix}$ ($\alpha \in \mathbb{C}$)

Then every FLT is a product of elliptic, hyperbolic, and parabolic transformations, due to the Jordan decomposition.

IV. Conformal mappings : generalities

Let's first nail down a definition.

let $U, V \subset \mathbb{C}$ be regions, and $F: U \rightarrow V$
a mapping with continuous partial derivatives.

Definition F is conformal on $\delta \subset U$ def. \iff

$F|_{\delta}$ preserves angles to first order \iff linear algebra

$(J_F(z))$ is of form $\begin{pmatrix} \alpha & \beta \\ -\beta & \alpha \end{pmatrix} (\forall z \in \delta)$ Lecture 2 \iff

$F|_{\delta}$ is holomorphic with nonvanishing derivative.

How do we know a holomorphic (or analytic)
map $f: U \rightarrow V$ is conformal?

I mean a
2-sided inverse.
I like.

Proposition If \exists holomorphic $g: V \rightarrow U$ inverting f ,
then f is conformal on all of U .

Proof: $1 = (g \circ f)'(z_0) = g'(f(z_0)) \cdot f'(z_0) \Rightarrow f'(z_0) \neq 0$. □

(It will turn out that 1-1 is enough.)

In this situation, f is said to be a holomorphic isomorphism $U \xrightarrow[\cong]{f} V$, and also (because of the proposition) a conformal equivalence.

When are 2 open sets in \mathbb{C} conformally equivalent? Here is a famous result:

Riemann Mapping Theorem Given $U \subsetneq \mathbb{C}$ a

simply connected region. Then there exists a conformal equivalence $f: U \xrightarrow[\cong]{f} D_1$.

Example // $U = h$, $f(z) := \frac{z-i}{z+i}$.

Claim: $h \xrightarrow[\cong]{f} D_1$.

Pf: $f(h) \subseteq D_1$: $z \in h \Rightarrow z = x+iy, y > 0$.

$$\begin{aligned}
 y > 0 &\Rightarrow y^2 - 2y + 1 < y^2 + 2y + 1 \\
 &\Rightarrow (y-1)^2 < (y+1)^2 \\
 &\Rightarrow |z-i|^2 < |z+i|^2 \\
 &\Rightarrow |z-i| < |z+i| \\
 &\Rightarrow |f(z)| < 1 \\
 &\Rightarrow f(z) \in D_1.
 \end{aligned}$$

Note: that
 f is $1-1$ follows
from the fact that
it is a FLT
(it has holomorphic inverse)

$$\begin{aligned}
 f(h) \in D_1 : w \in D_1 &\Rightarrow \operatorname{Im} \left(-i \frac{w+1}{w-1} \right) \\
 &= \operatorname{Re} \left(-\frac{w+1}{w-1} \right) \\
 &= \operatorname{Re} \left(-\frac{(w+1)(\bar{w}-1)}{|w-1|^2} \right) \\
 &= \operatorname{Re} \left(-\frac{|w|^2 - 1 + \bar{w} - w}{|w-1|^2} \right) \\
 &= \frac{1 - |w|^2}{|w-1|^2} > 0 \\
 &\Rightarrow -i \frac{w+1}{w-1} \in h.
 \end{aligned}$$

$$\text{Now } f \left(-i \frac{w+1}{w-1} \right) = \frac{-i \frac{w+1}{w-1} - i}{-i \frac{w+1}{w-1} + i} = \frac{w+1 + (w-1)}{w+1 - (w-1)} = w, \quad \text{done.} \quad \square$$

Picture:

